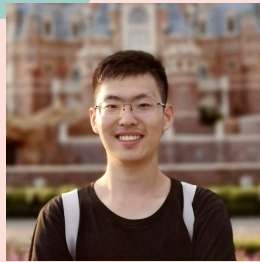


Computing a Fixed Point of Contraction Maps in Polynomial Queries



Xi Chen
Columbia



Yuhao Li
Columbia



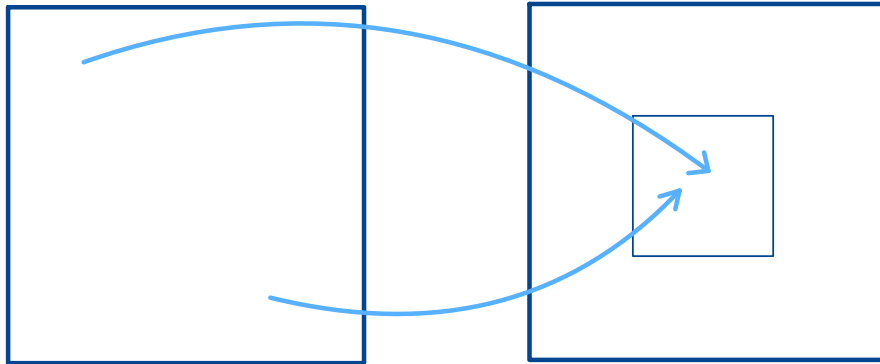
Mihalis Yannakakis
Columbia

Game and Equilibria workshop, 2024

CONTRACTION FIXED POINT

Def. A map $f: [0,1]^k \mapsto [0,1]^k$ is a $\gamma \in (0,1]$ $(1-\gamma)$ -contraction if

$$\|f(x) - f(y)\|_{\infty} \leq (1-\gamma) \|x - y\|_{\infty} \quad \forall x, y \in [0,1]^k.$$



CONTRACTION FIXED POINT

Def. A map $f: [0,1]^k \mapsto [0,1]^k$ is a $(1-\gamma)$ -contraction if $\gamma \in (0,1]$

$$\|f(x) - f(y)\|_\infty \leq (1-\gamma) \|x - y\|_\infty \quad \forall x, y \in [0,1]^k.$$

Theorem. [Banach (1922)]

Every contraction map has a unique fixed point.

$$x^* = f(x^*)$$

APPLICATIONS OF BANACH FIXED POINT

Mathematics:

Picard-Lindelof (Cauchy-Lipschitz) theorem

Nash embedding theorem

Computer science:

Markov decision processes

Underlie many classic dynamic programming problems

Subsume stochastic/mean-payoff/parity games

Theorem. [Banach (1922)]

Every contraction map has a unique fixed point.

QUERY MODEL

- * We have a query access to the function f .
- * Find an ε -approx. fixed point by as few queries as possible.

$$\uparrow$$
$$|f(x) - x|_{\infty} \leq \varepsilon$$

QUERY MODEL

- * We have a query access to the function f .
- * Find an ε -approx. fixed point by as few queries as possible.

$$\uparrow$$
$$|f(x) - x|_{\infty} \leq \varepsilon$$

Remark on approximation.

- o The exact fixed point may be irrational.
- o ε -approximate fixed point suffices.

QUERY MODEL

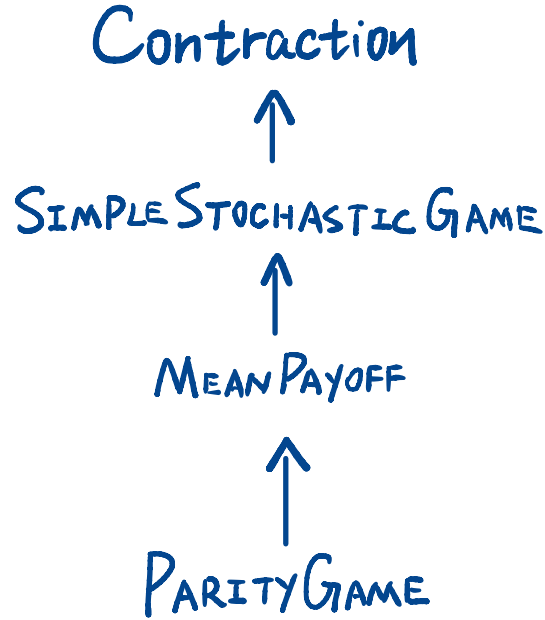
- * We have a query access to the function f .
- * Find an ε -approx. fixed point by as few queries as possible.

$$\uparrow$$
$$|f(x) - x|_{\infty} \leq \varepsilon$$

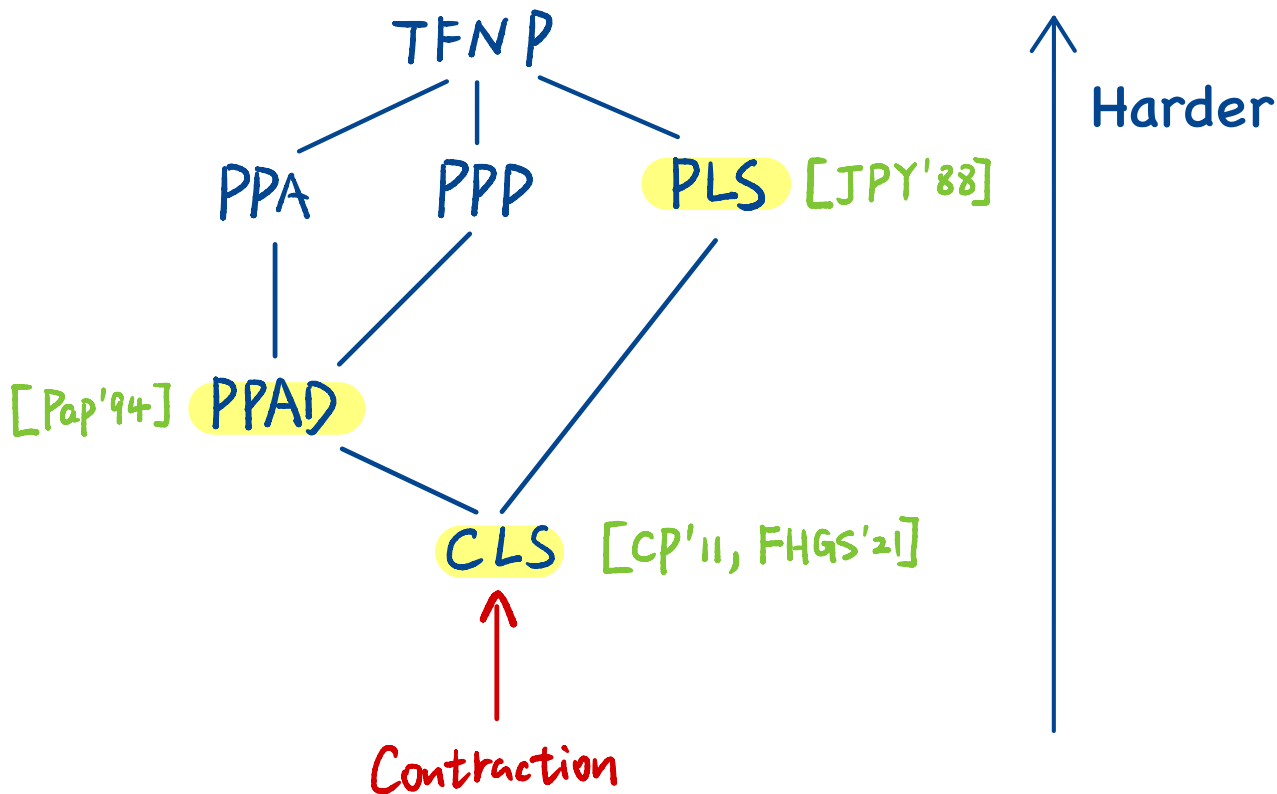
SOTA: $O(\log^k(1/\varepsilon))$. [Shellman, Sikorski 03]

Goal. $\text{poly}(k, \log(1/\varepsilon), \log(1/r))$.

MOTIVATION



INTRIGUING STATUS



CONSTRUCTIVE EXISTENCE

Observation. Start from any point x_0 and follow the path

$$x_1 = f(x_0), x_2 = f(x_1) \dots$$

$$\text{Then } |x_{n+1} - x_n|_\infty \leq (1-r)^n.$$

Claim. This sequence converges to a fixed point.

CONSTRUCTIVE EXISTENCE

Observation. Start from any point x_0 and follow the path

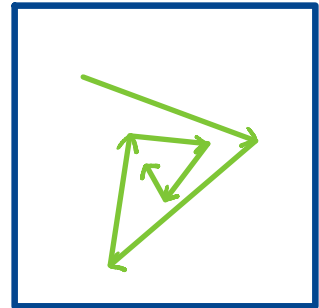
$$x_1 = f(x_0), x_2 = f(x_1) \dots$$

$$\text{Then } |x_{n+1} - x_n|_\infty \leq (1-\gamma)^n.$$

Claim. This sequence converges to a fixed point.

In fact, after $n \approx \frac{1}{\gamma} \cdot \log(1/\epsilon)$ steps, we have

$$|f(x_n) - x_n|_\infty = |x_{n+1} - x_n|_\infty \leq (1-\gamma)^n \leq \epsilon.$$



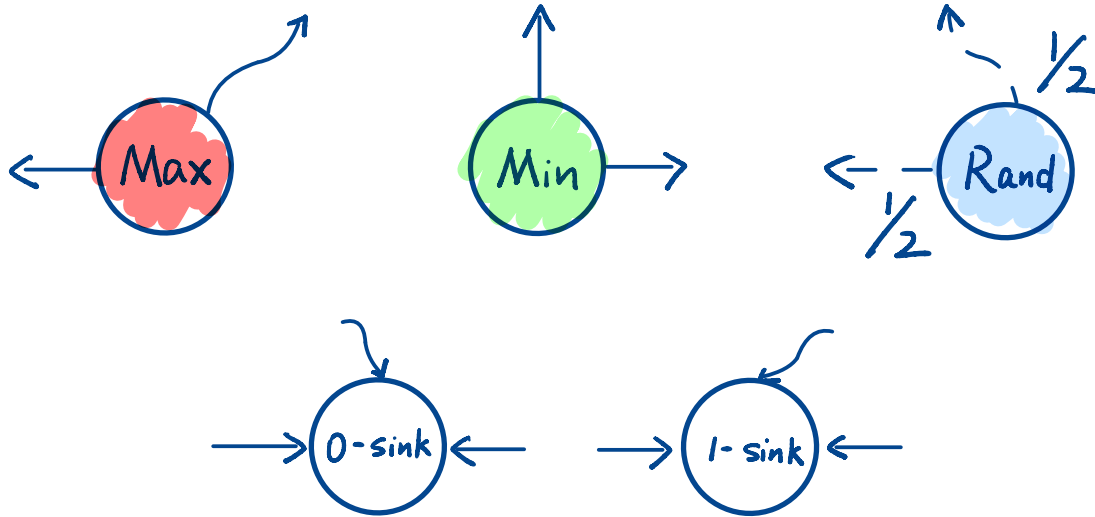
MOTIVATION



↑
Harder

SIMPLE STOCHASTIC GAME

[Condon (1992)]

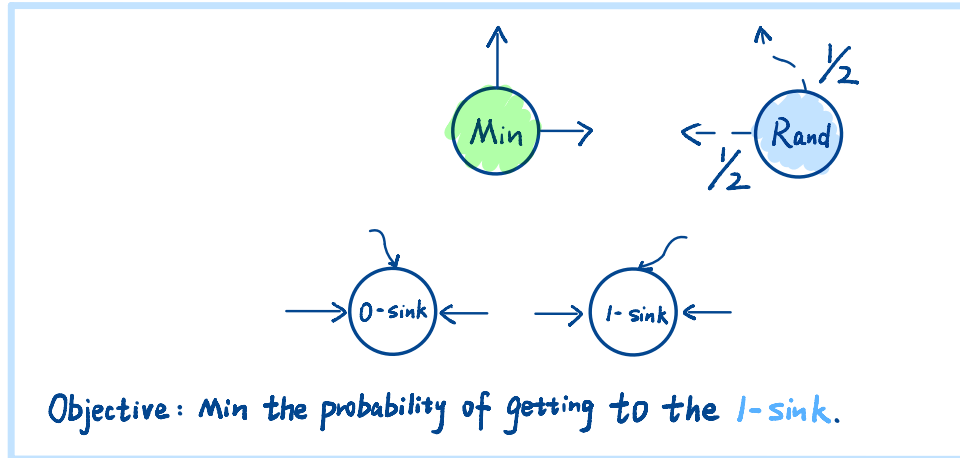


Objective: Max/Min the probability of getting to the 1-sink.

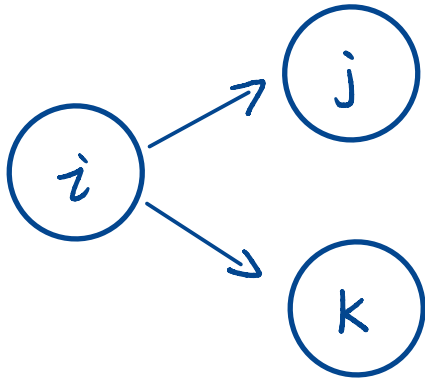
COMPLEXITY OF SSG: $NP \cap co-NP$

Decision problem: if $P[\text{player 1 wins}] > \frac{1}{2}$.

One player version can be solved in polytime $\Rightarrow NP \cap co-NP$.



COMPLEXITY OF SSG: $UP \cap co-UP$



$$v_i = \begin{cases} \max \{v_j, v_k\} & i \in V_{\max} \\ \min \{v_j, v_k\} & i \in V_{\min} \\ \frac{1}{2} (v_j + v_k) & i \in V_{\text{rand}} \end{cases}$$

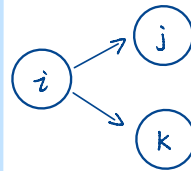
$$v_{0\text{-sink}} = 0 \quad v_{1\text{-sink}} = 1$$

Denote this system of equations by $v = F(v)$.

COMPLEXITY OF SSG: $UP \cap co-UP$

* $F: [0,1]^n \rightarrow [0,1]^n$ is a **non-expansive** map.

$$|F(x) - F(y)|_{\infty} \leq |x - y|_{\infty}.$$



$$v_i = \begin{cases} \max \{v_j, v_k\} & i \in V_{\max} \\ \min \{v_j, v_k\} & i \in V_{\min} \\ \frac{1}{2}(v_j + v_k) & i \in V_{\text{rand}} \end{cases}$$

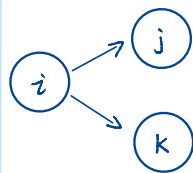
$$v_{0\text{-sink}} = 0 \quad v_{1\text{-sink}} = 1$$

Denote this system of equations by $v = F(v)$.

COMPLEXITY OF SSG: $UP \cap co-UP$

* $F: [0,1]^n \rightarrow [0,1]^n$ is a **non-expansive** map.

* Let $F^\delta := (1-\delta)F$. Becomes a $(1-\delta)$ -contraction.



$$v_i = \begin{cases} \max \{v_j, v_k\} & i \in V_{\max} \\ \min \{v_j, v_k\} & i \in V_{\min} \\ \frac{1}{2}(v_j + v_k) & i \in V_{\text{rand}} \end{cases}$$

$$v_{0-\text{sink}} = 0 \quad v_{1-\text{sink}} = 1$$

Denote this system of equations by $v = F(v)$.

COMPLEXITY OF SSG: $UP \cap co-UP$

- Banach fixed point theorem \Rightarrow unique fixed point.

- In this case, the unique fixed point is guaranteed

rational + poly bit description.

* $F: [0,1]^n \rightarrow [0,1]^n$ is a non-expansive map.

* Let $F^\delta := (1-\delta)F$. Becomes a $(1-\delta)$ -contraction.

COMPLEXITY OF SSG: $UP \cap co-UP$

• Banach fixed point theorem \Rightarrow unique fixed point.

• In this case, the unique fixed point is guaranteed

rational + poly bit description.

Remark.

ϵ -approximate fixed point surfaces.

Both ϵ and δ need to be $\frac{1}{2}^{\text{poly}(n)}$.

* $F: [0,1]^n \rightarrow [0,1]^n$ is a non-expansive map.

* Let $F^\delta := (1-\delta)F$. Becomes a $(1-\delta)$ -contraction.

MOTIVATION

Contraction ($\epsilon, \delta = \frac{1}{2} \text{poly}(n)$)



SIMPLE STOCHASTIC GAME



MEAN PAYOFF



PARITY GAME

Pseudo-poly time

[Zwick, Paterson 96]

Quasi-poly time

[Calude, Jain, Khousainov, Li, Stephan 17]

WHY QUERY MODEL?

We have such an explicit function:

$$V_i = \begin{cases} \max \{V_j, V_k\} & i \in V_{\max} \\ \min \{V_j, V_k\} & i \in V_{\min} \\ \frac{1}{2}(V_j + V_k) & i \in V_{\text{rand}} \end{cases}$$

$$V_{0\text{-sink}} = 0 \quad V_{1\text{-sink}} = 1$$

WHY QUERY MODEL?

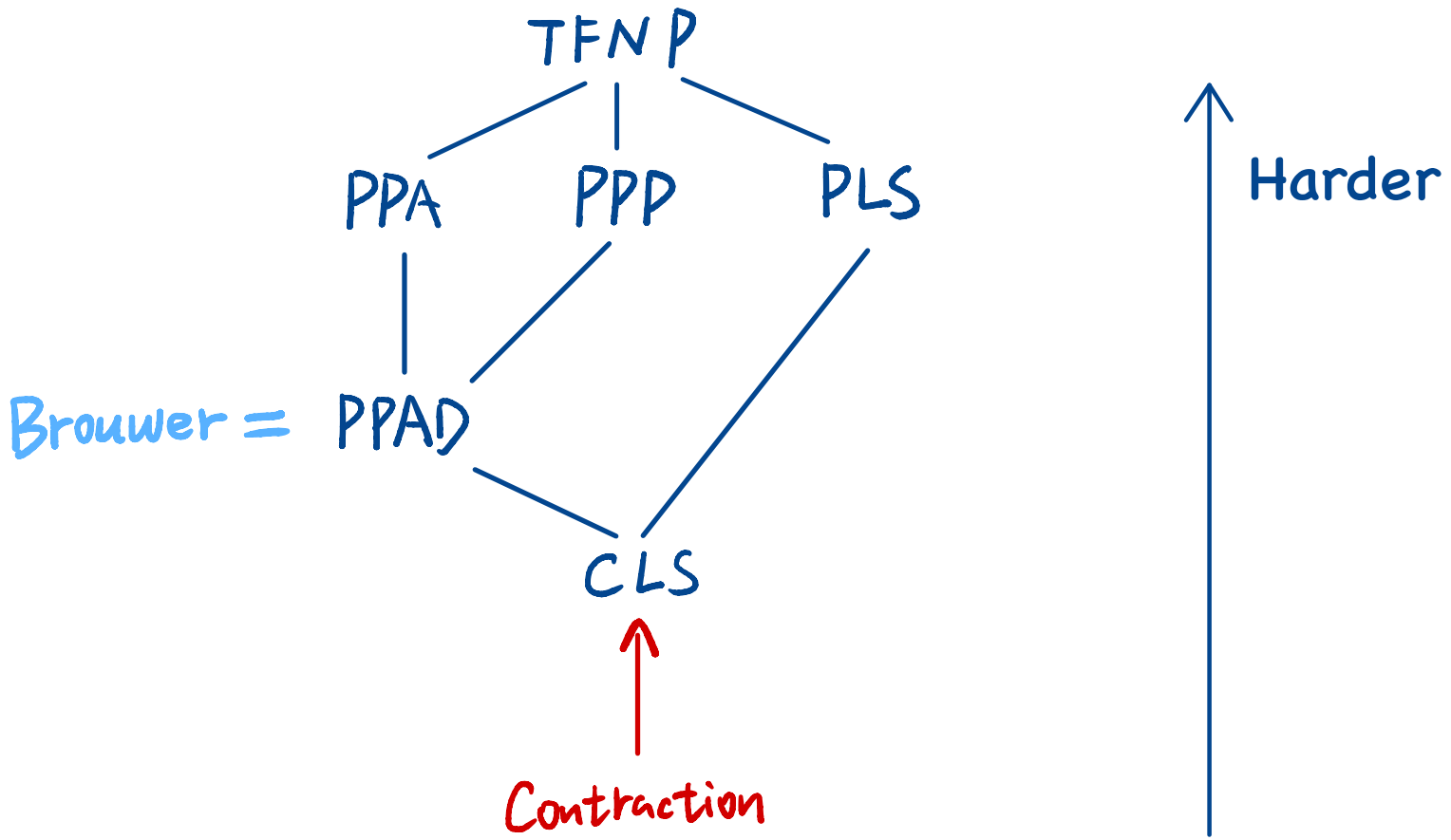
We have such an explicit function:

$$V_i = \begin{cases} \max \{V_j, V_k\} & i \in V_{\max} \\ \min \{V_j, V_k\} & i \in V_{\min} \\ \frac{1}{2} (V_j + V_k) & i \in V_{\text{rand}} \end{cases}$$

$V_{0\text{-sink}} = 0 \quad V_{1\text{-sink}} = 1$

Unfortunately, we don't know how to work on them beyond evaluating function values...

Another more well-understood example: Brouwer



BROUWER FIXED POINT

Def. A map $f: [0,1]^k \mapsto [0,1]^k$ is L -Lipschitz if $L \in (0, \infty)$

$$\|f(x) - f(y)\|_{\infty} \leq L \cdot \|x - y\|_{\infty} \quad \forall x, y \in [0,1]^k.$$

Theorem. [Brouwer (1911)]

Every continuous function $f: \Delta^k \rightarrow \Delta^k$ has a fixed point.

BROUWER FIXED POINT

Def. A map $f: [0,1]^k \mapsto [0,1]^k$ is L -Lipschitz if $L \in (0, \infty)$

$$\|f(x) - f(y)\|_{\infty} \leq L \cdot \|x - y\|_{\infty} \quad \forall x, y \in [0,1]^k.$$

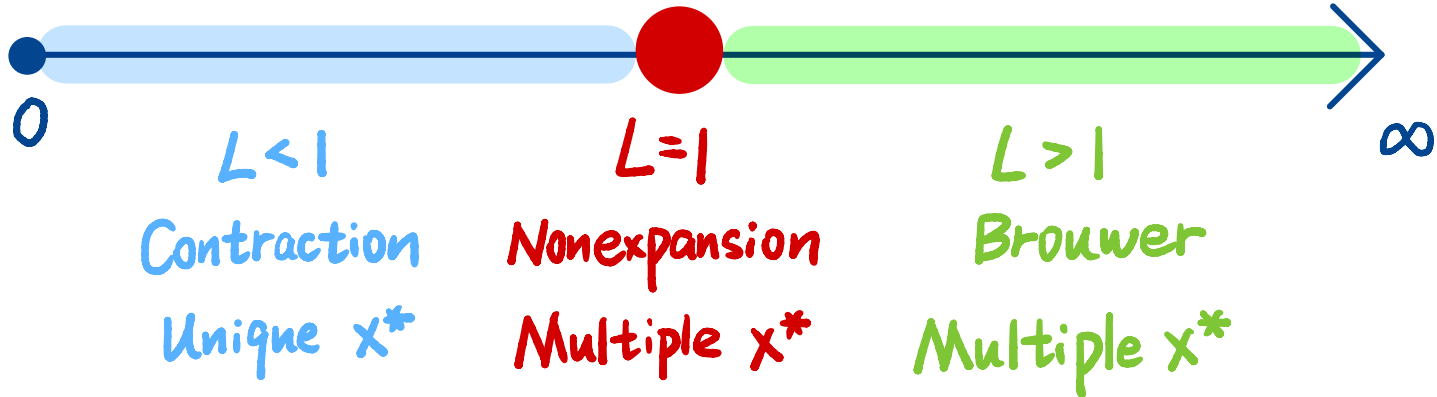
Theorem. [Brouwer (1911)]

Every continuous function $f: [0,1]^k \rightarrow [0,1]^k$ has a fixed point.

BROUWER FIXED POINT

Def. A map $f: [0,1]^k \mapsto [0,1]^k$ is L -Lipschitz if

$$|f(x) - f(y)|_{\infty} \leq L \cdot |x - y|_{\infty} \quad \forall x, y \in [0,1]^k.$$



COMPLEXITY OF BROUWER

- * Exponential query lower bound [HPV'89, CD'08]
- * PPAD-complete (widely believed $\neq P$)
- * How about important explicit functions?

NASH EQUILIBRIUM

Theorem 23 (Nash 1951) *Every game with a finite number of players and action profiles has at least one Nash equilibrium.*

Proof. Given a strategy profile $s \in S$, for all $i \in N$ and $a_i \in A_i$ we define

$$\varphi_{i,a_i}(s) = \max\{0, u_i(a_i, s_{-i}) - u_i(s)\}.$$

We then define the function $f : S \rightarrow S$ by $f(s) = s'$, where

$$\begin{aligned} s'_i(a_i) &= \frac{s_i(a_i) + \varphi_{i,a_i}(s)}{\sum_{b_i \in A_i} s_i(b_i) + \varphi_{i,b_i}(s)} \\ &= \frac{s_i(a_i) + \varphi_{i,a_i}(s)}{1 + \sum_{b_i \in A_i} \varphi_{i,b_i}(s)}. \end{aligned} \tag{5}$$

NASH EQUILIBRIUM

Theorem. [DGP'06, CDT'06]

Computing a Nash equilibrium in a 2-player game
is PPAD-complete.

“Computing a Nash equilibrium
is as hard as
computing a general Brouwer fixed point.”

COMPLEXITY OF CONTRACTION?

Contraction ($\epsilon, \delta = \frac{1}{2} \text{poly}(n)$)



SIMPLE STOCHASTIC GAME



MEAN PAYOFF



PARITY GAME

QUERY MODEL

- * We have a query access to the function f .
- * Find an ε -approx. fixed point by as few queries as possible.

$$\uparrow$$
$$|f(x) - x|_{\infty} \leq \varepsilon$$

Efficient. $\text{poly}(k, \log(1/\varepsilon), \log(1/r))$.

POLY-QUERY ALGORITHM!

Our Main Result.

An $O(k^2 \cdot \log(1/\epsilon))$ query algorithm for CONTRACTION (k, ϵ, δ) .

QUERY MODEL

- * We have a query access to the function f .
- * Find an ϵ -approx. fixed point by as few queries as possible.

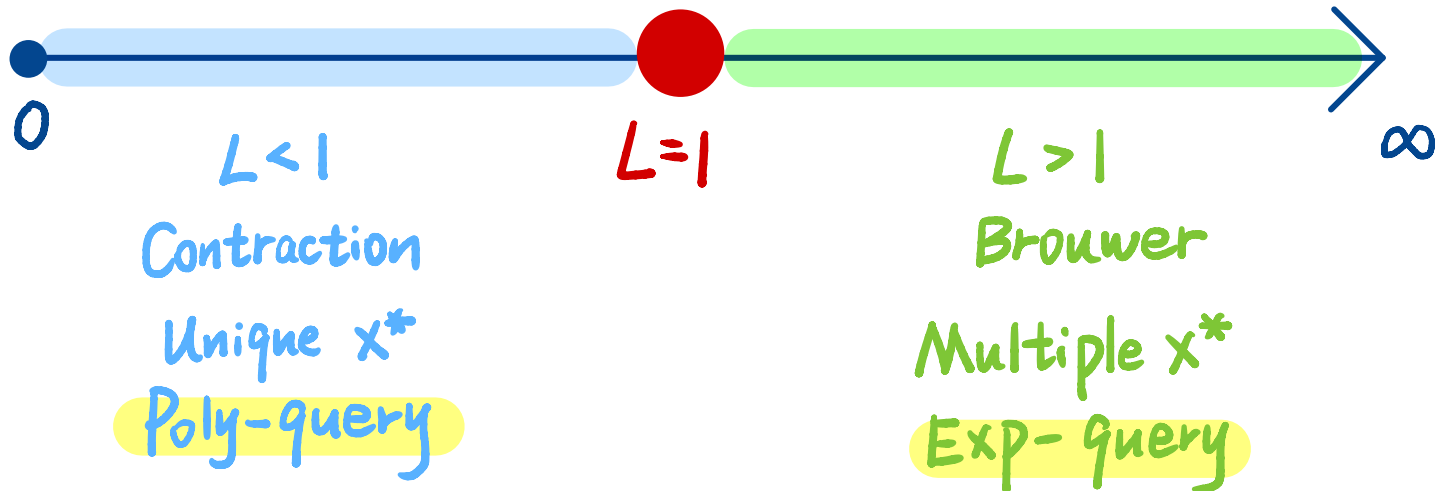
$$\uparrow \\ |f(x) - x|_{\infty} \leq \epsilon$$

Efficient. $\text{poly}(k, \log(1/\epsilon), \log(1/\delta))$.

POLY-QUERY ALGORITHM!

Our Main Result.

An $O(k^2 \cdot \log(1/\epsilon))$  query algorithm for CONTRACTION (k, ϵ, δ) .



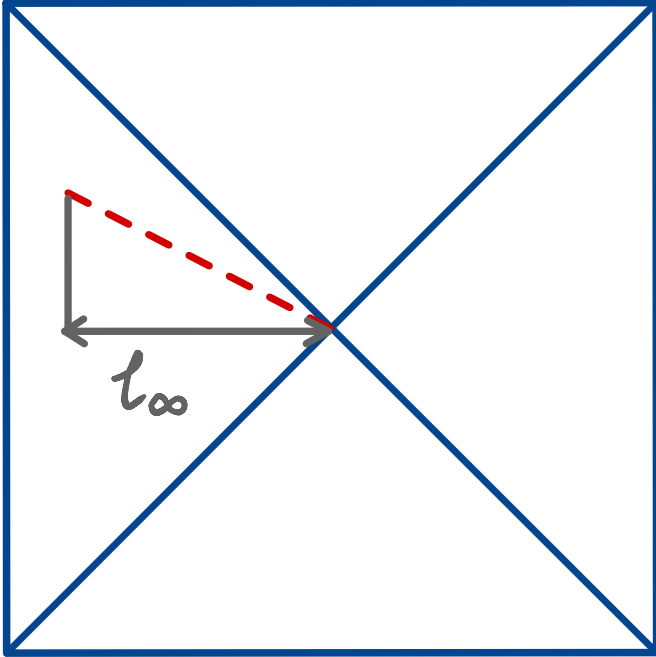
POLY-QUERY ALGORITHM!

Our Main Result.

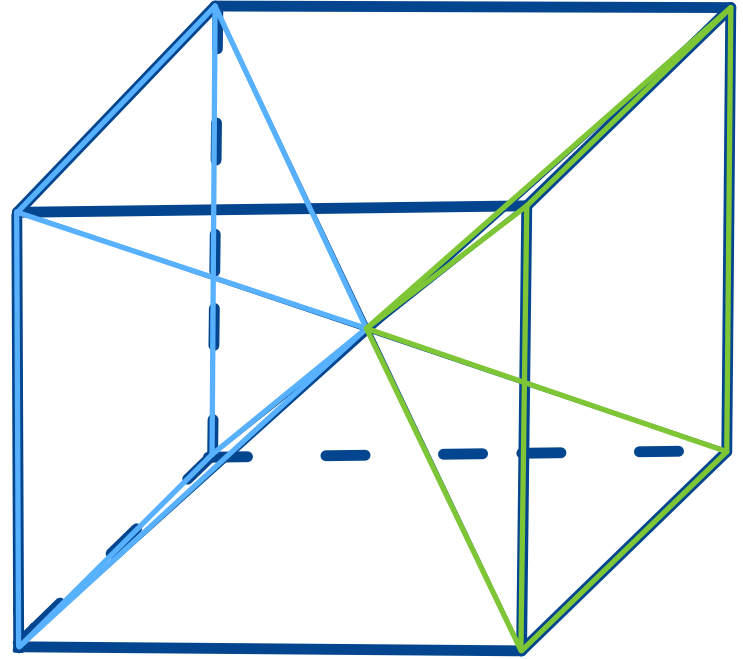
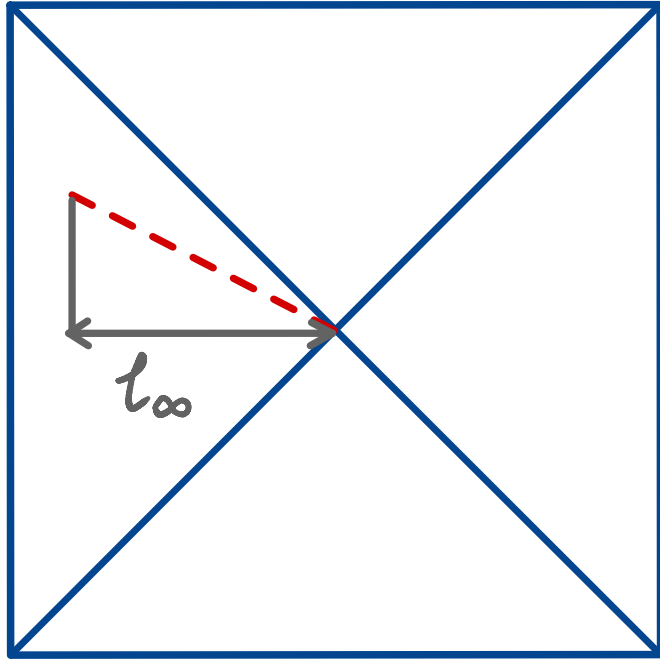
An $O(k^2 \cdot \log(1/\epsilon))$ query algorithm for CONTRACTION (k, ϵ, δ) .

This makes contraction in a very intriguing complexity status!

TECHNIQUES

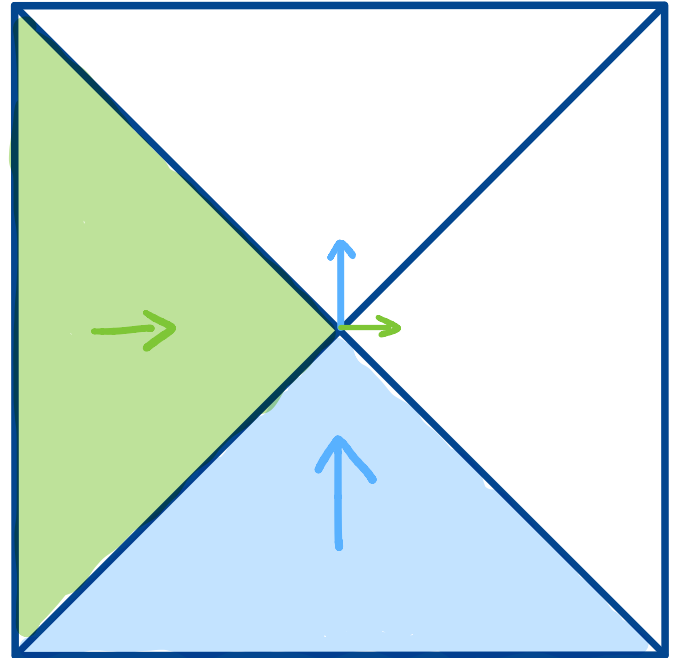
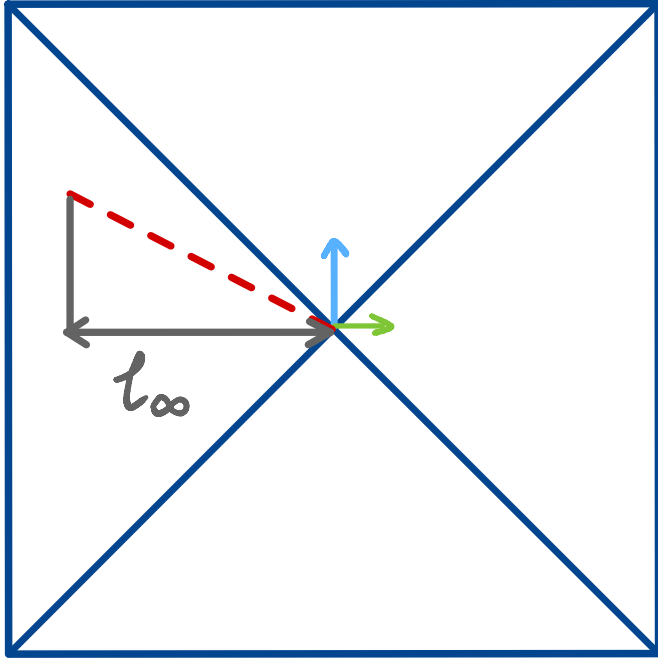


TECHNIQUES

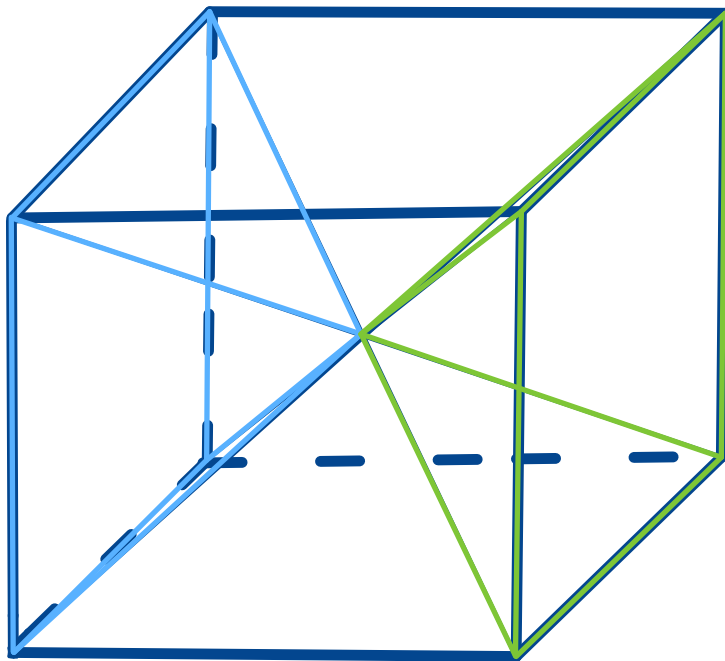


Pyramid

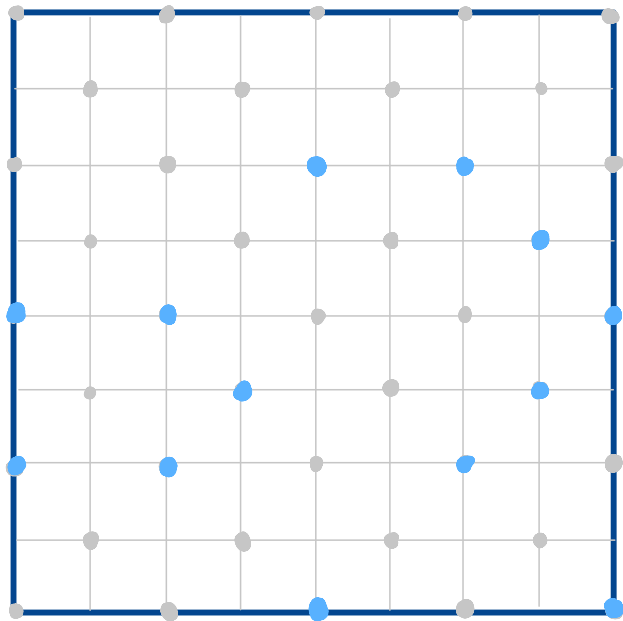
TECHNIQUES



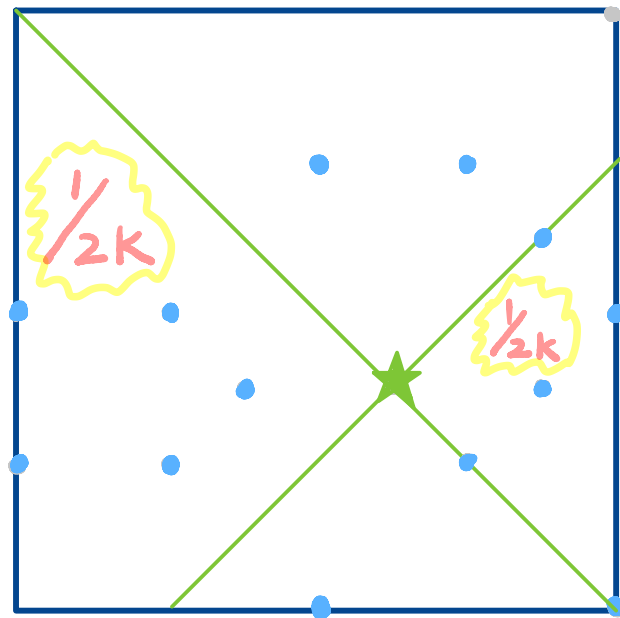
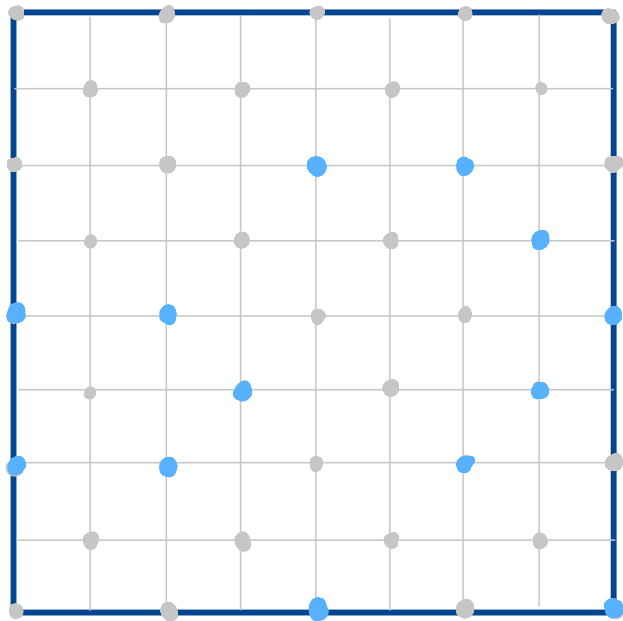
NON-CONVEX FOR 3-D



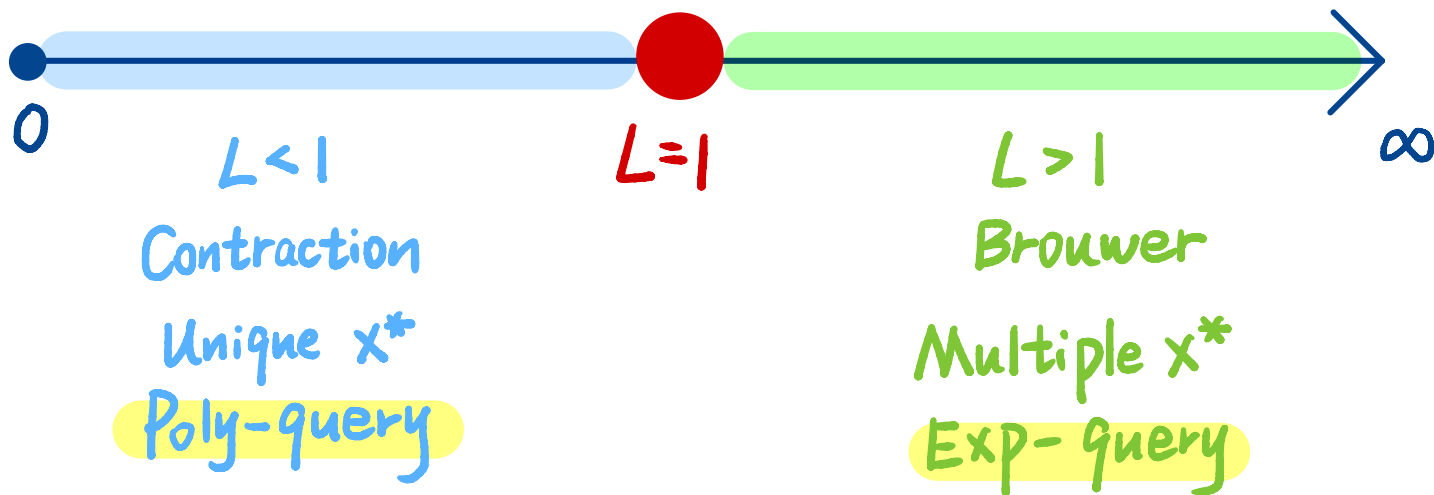
BALANCED POINT



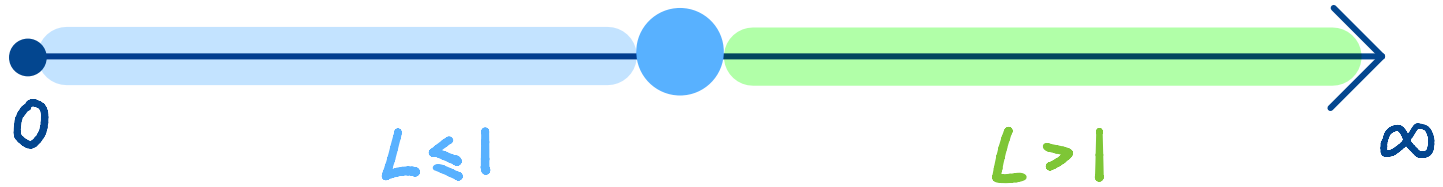
BALANCED POINT



HOW ABOUT $L=1$?



WEAK APPROXIMATION

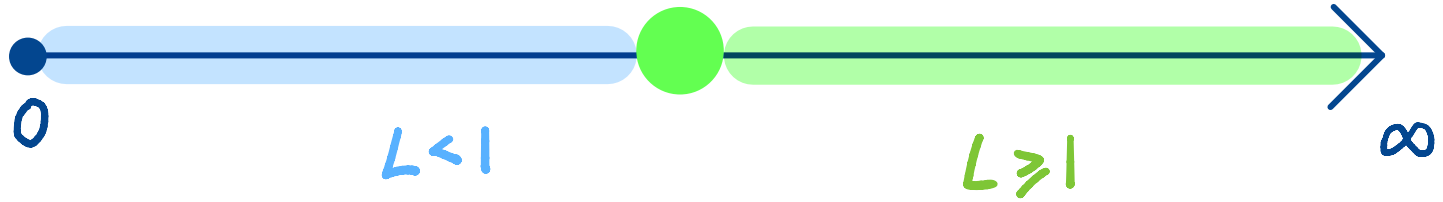


Poly-query

Exp-query

Weak approximation: $|f(x) - x|_{\infty} \leq \epsilon$

STRONG APPROXIMATION

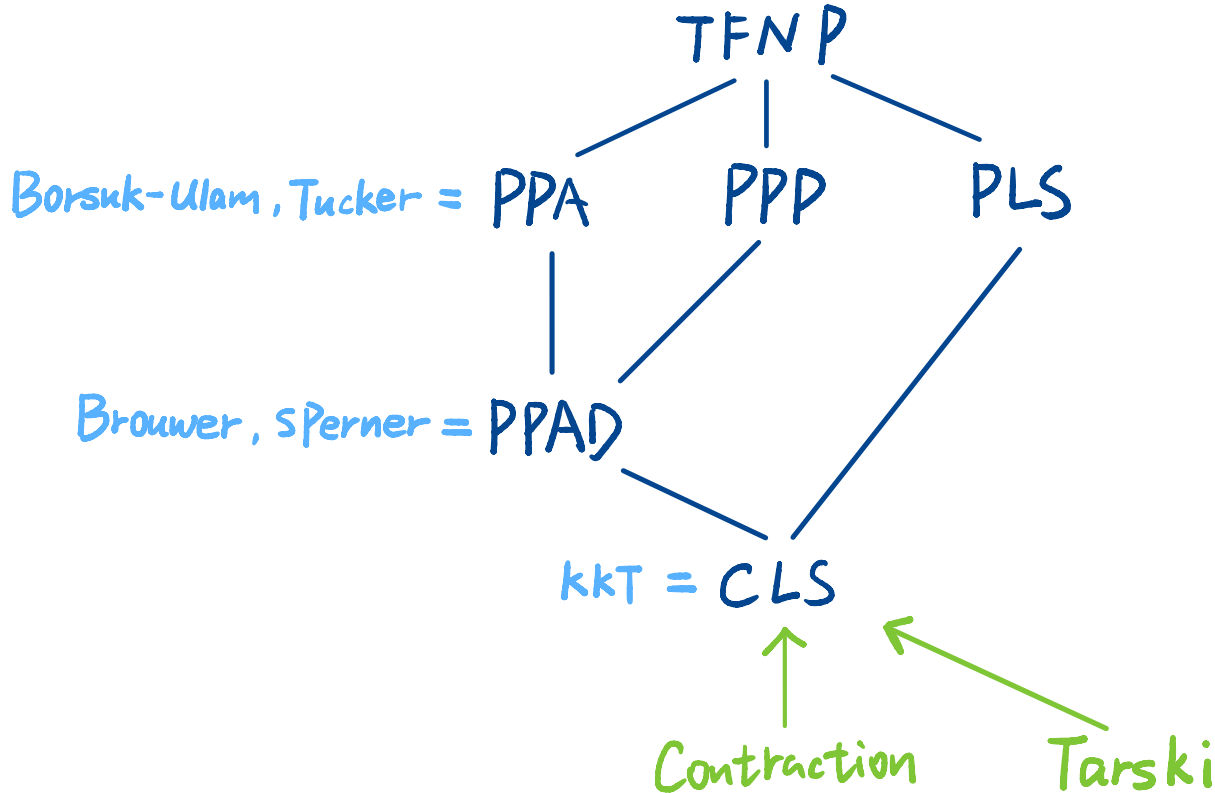


Poly-query

Infinite-query

Strong approximation: $\|x - x^*\|_{\infty} \leq \varepsilon$

FIXED POINT COMPUTATION

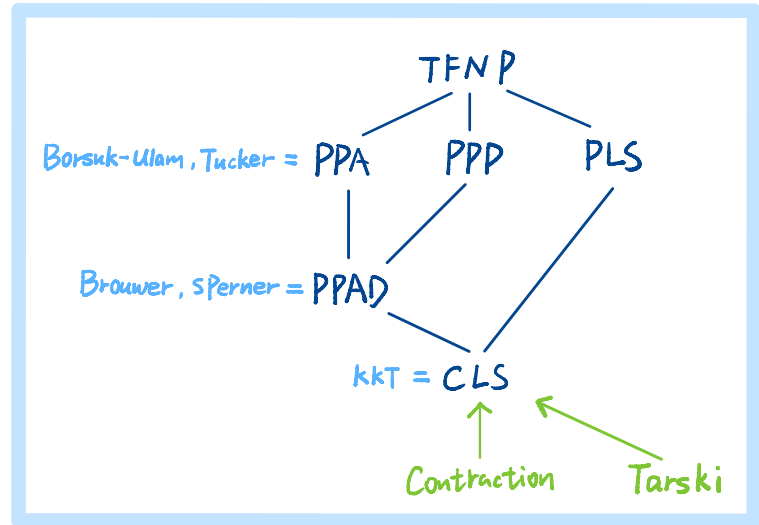


INTRIGUING STATUS

* In $CLS = PLS \wedge PPAD$

* Not known query lower bound

Tarski
Contraction

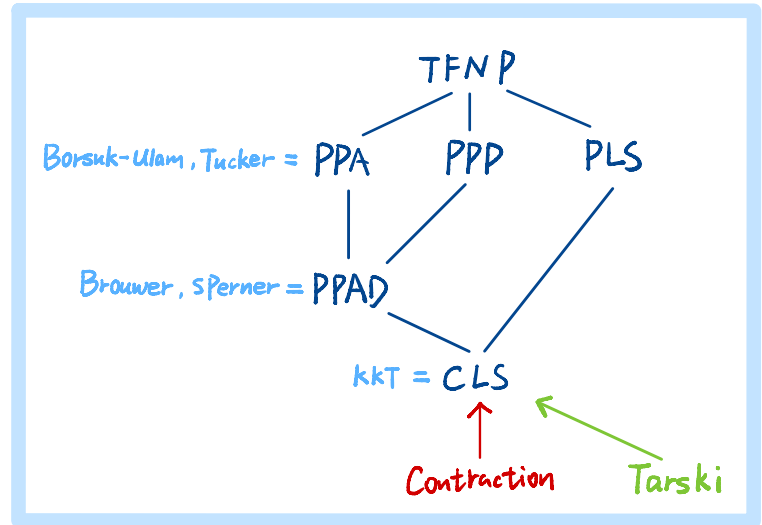


CONTRACTION: MORE INTRIGUING

* In $CLS = PLS \cap PPAD$

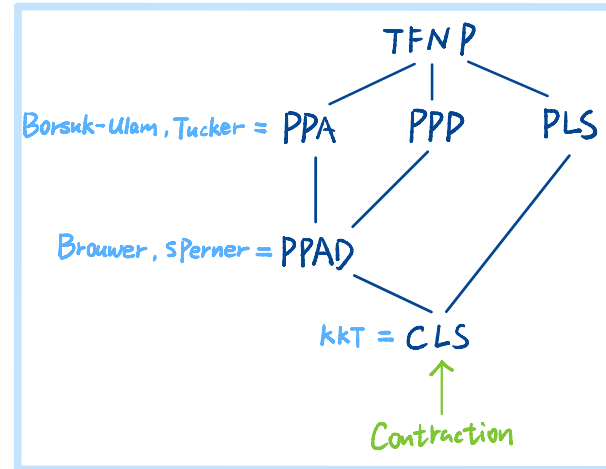
~~* Not known query lower bound~~

* Query lower bound is impossible!



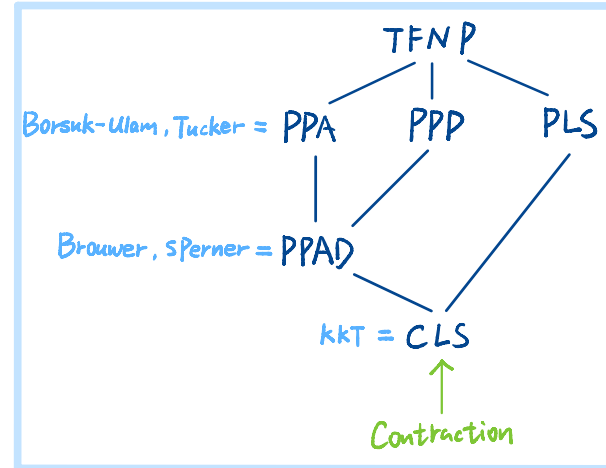
INTERPRETATION

- * All other fixed points that are complete for their corresponding classes have exponential query L.B.
- * The story for contraction is completely different.



INTERPRETATION

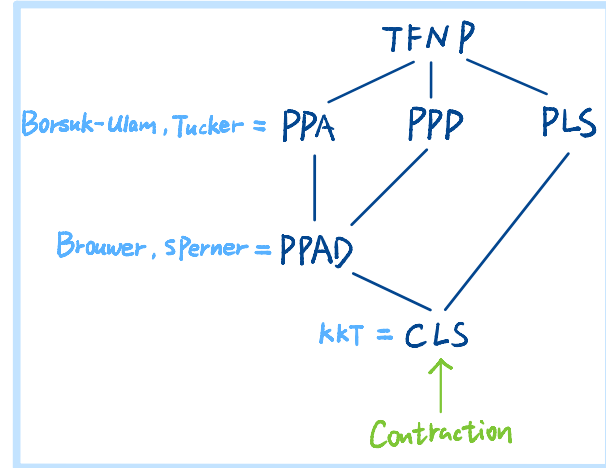
① Hardness? Need to go beyond traditional wisdom about hardness in TFNP.



INTERPRETATION

- ① Hardness? Need to go beyond traditional wisdom about hardness in TFNP.
- ② We hope that it helps design time-efficient algs for contraction/SSGs.

Ultimately, poly-time algs.



OPEN PROBLEMS

* Time complexity for contraction.

* How about other p -norm ?

The only known result is poly-query and poly-time algorithm for 2-norm. [STW'93, HKS'99]

THANKS !

xichen@cs.columbia.edu

yuhaoLi@cs.columbia.edu

mihalis@cs.columbia.edu

